### **DeepPlace: Learning to Place Applications in Multi-Tenant Clusters**

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#### **Collaborators**

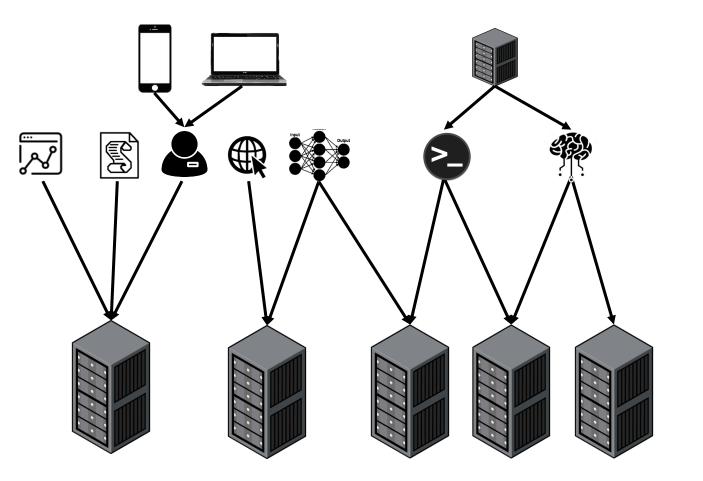
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#### \* work done while at Adobe Research

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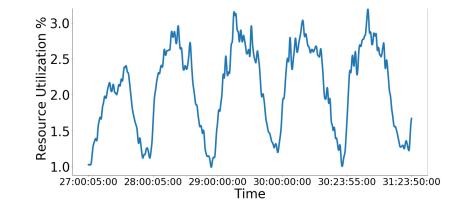
## The Multi-Tenant Computation Landscape

- Variety of Applications
  - Ex: User-facing, Batch Analytics, etc.
- Variety of Resource Needs
  - Ex: Resource intensive
- Variety of User Expectations
  - Ex: Latency Sensitive



## **Improving Variance – Through Resource Limits**

- Developers Can specify Resource Limits.
- Overly Conservative estimates.
  - For adverse situation.
- Poor utilization.
  - Peak is (way) less than estimated.
  - Peak doesn't remain for majority of time.



# **Improving Variance – Through Constraints**

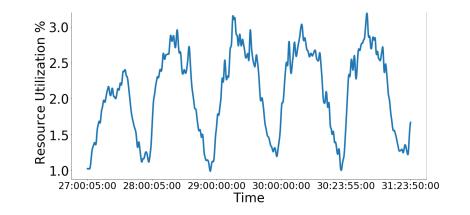
- To give better control to developers, schedulers provide ways to specify constraints.
- Based on estimates (generally conservative) and heuristics.
- Issue Limited Expressibility



#### Placement Constraints in Marathon (Apache Mesos)

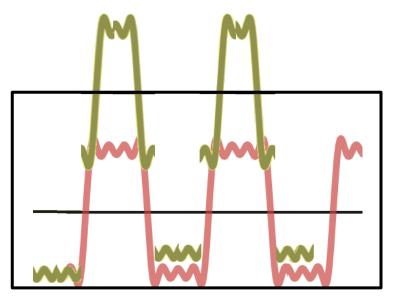
## Where they fail – Temporal Patterns

- Temporal Patterns
  - Across Time (ex. Daily, Seasonal, etc.)
  - Across Algorithmic Phases (ex. Map-Reduce, etc.)
- Long-running Jobs
  - More peaks and valleys.
  - Relatively high predictability.
- Short-running Jobs
  - Can fit in valleys of long-running.
  - Though less predictability.

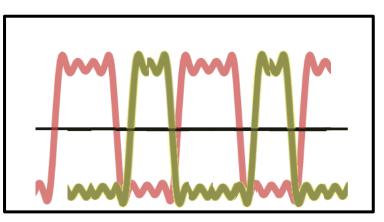


# Where they fail – Temporal Alignment

- Minor temporal mis-alignment can lead to inefficient scheduling.
- Placement 1 overshoots the resource usage while Placement 2 efficiently completes.



Placement 1 - Temporally Mis-aligned (Overshoots)

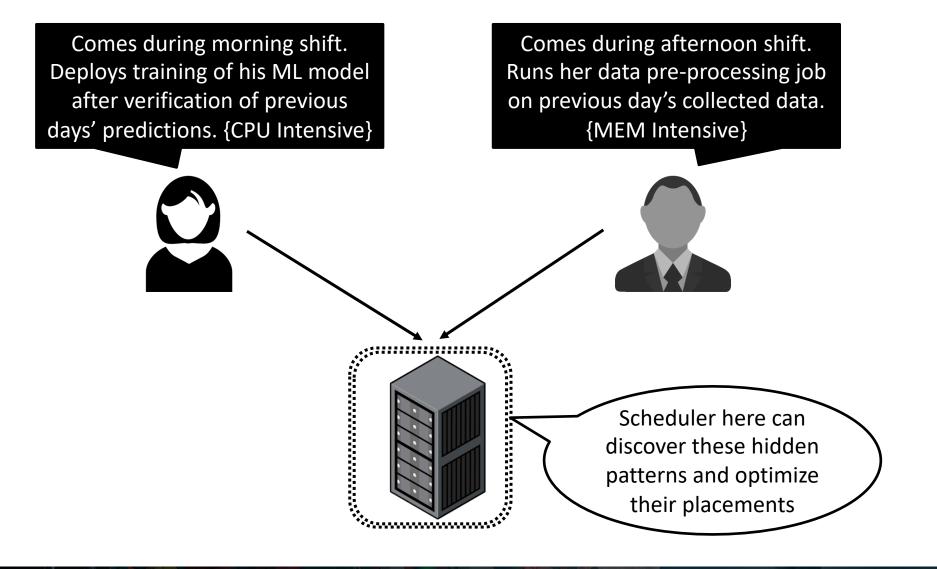


Placement 2 - Temporally Aligned

M Job 1

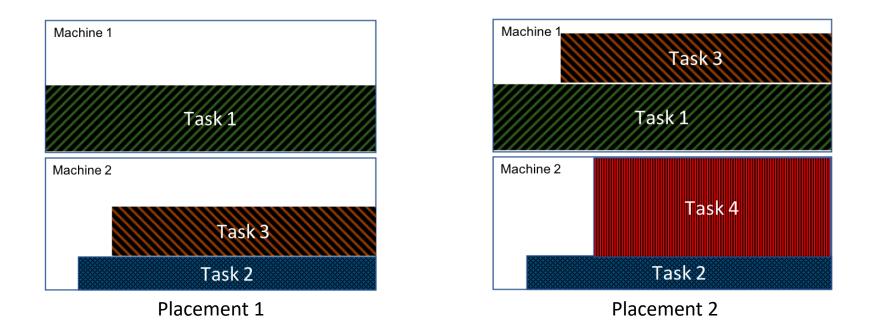
Job 2

### Where they fail – Job "Dependencies"



## Where they fail – Fragmentation

Given load be "Task 1 (0.5r), Task2 (0.25r), Task 3 (0.375r) and Task 4 (0.75r)"



- Placement 1 Although same total resources available, but is fragmented.
- Placement 2 Able to schedule all 4 tasks.

## What should be done?

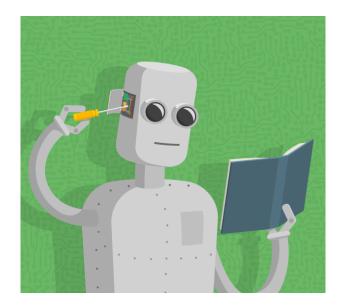
At a scheduling decision

- Analyze current state of all the machines.
- Decide on which machine to place the next application.
- Observe the benefits obtained from this decision.
- Improve our decisions based on these observations.

# **Formalizing It**

Build a *self-learning* scheduler to *opportunistically* place containerized applications such that

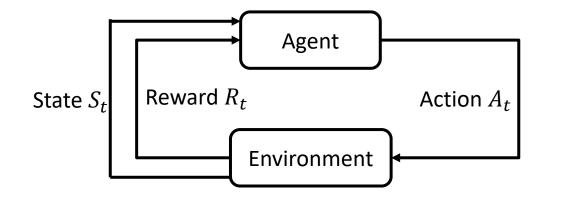
- Temporal Usages are aligned,
- Resource Contentions are minimized,
- Quality of Service is maintained and
- **Overall Resource Utilization** improved.



### What should be done?

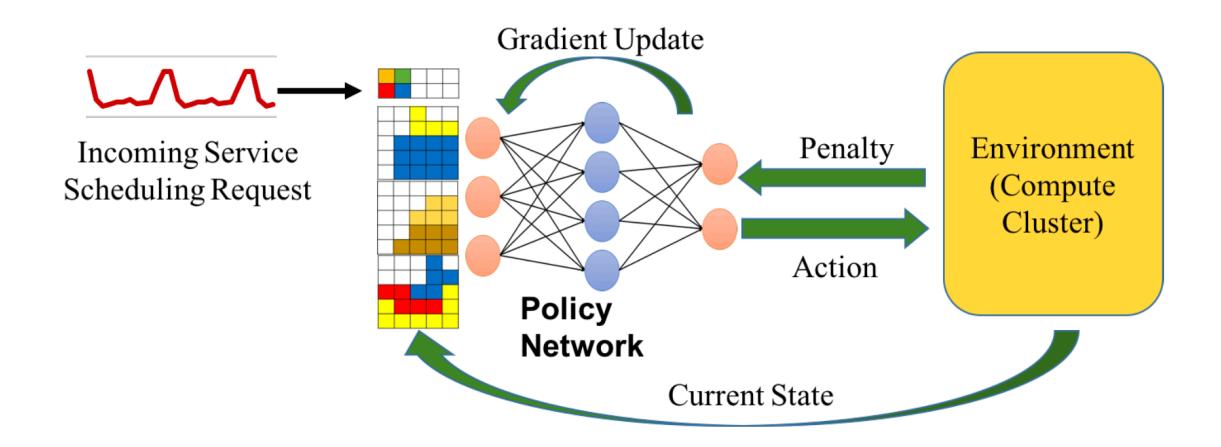
At a scheduling decision

- Analyze current state of all the machines State Representation (S<sub>t</sub>)
- Decide on which machine to place the next application Action Space (A<sub>t</sub>)
- Observe the benefits obtained from this decision Reward Function (R<sub>t</sub>)
- Improve our decisions based on these observations Policy Network (π)

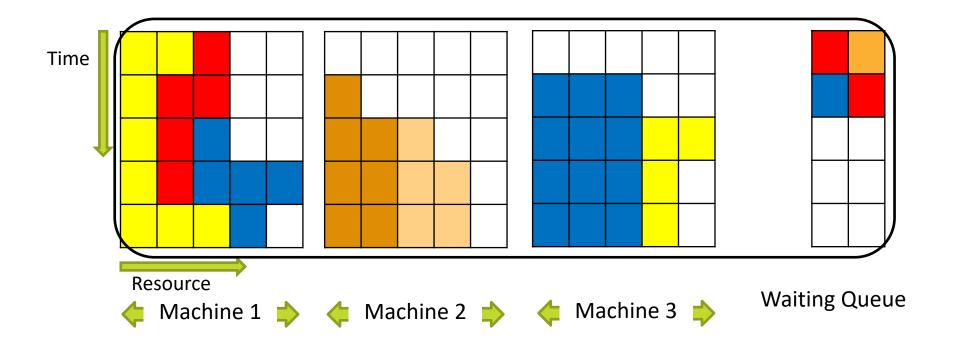


Leads to a natural map to a **Reinforcement Learning Problem**!

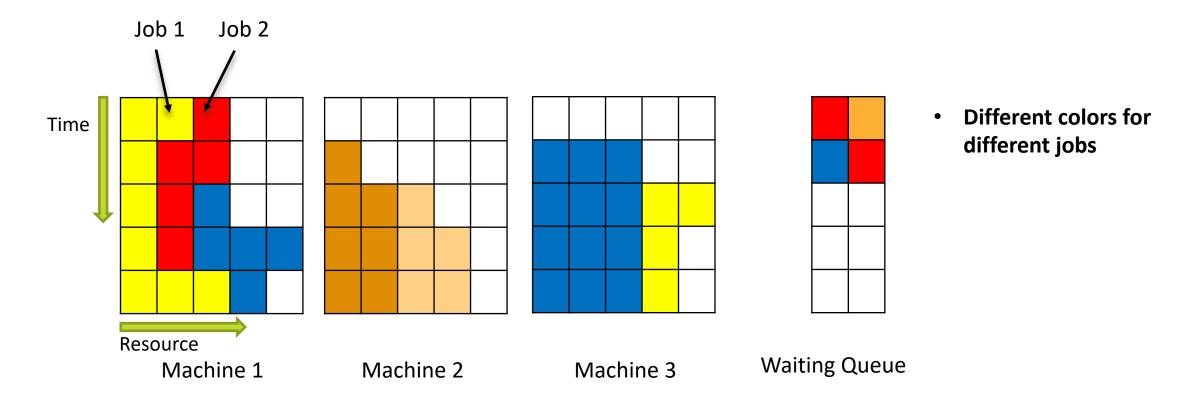
### **Solution – Workflow**



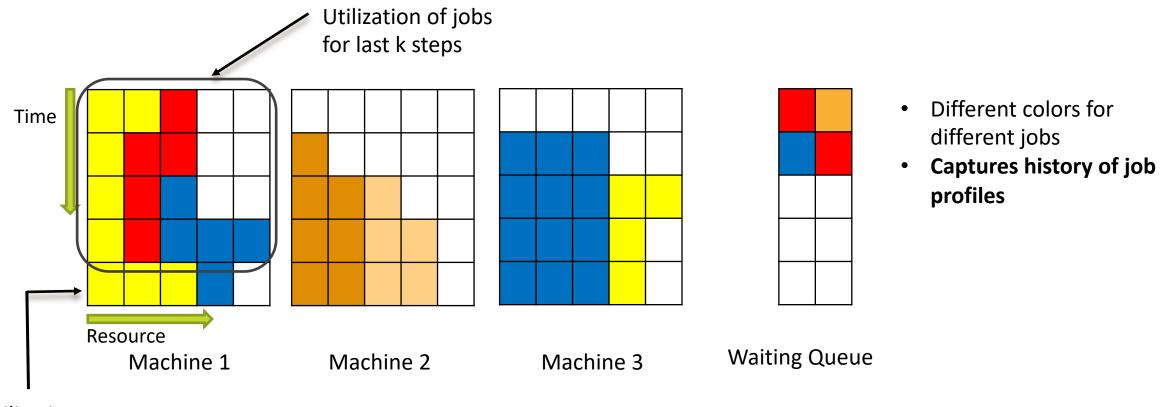
### **1. State Representation**



# 1. State Representation (2)

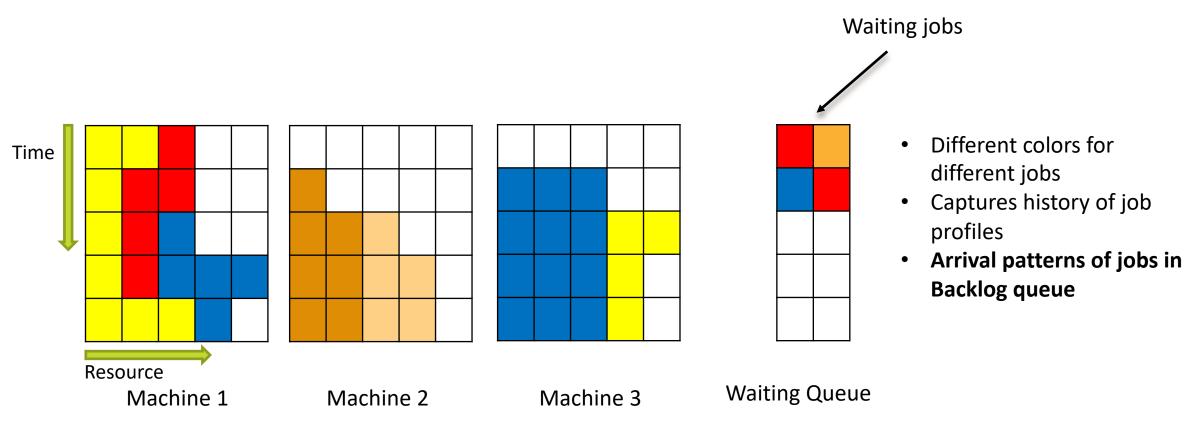


# 1. State Representation (3)

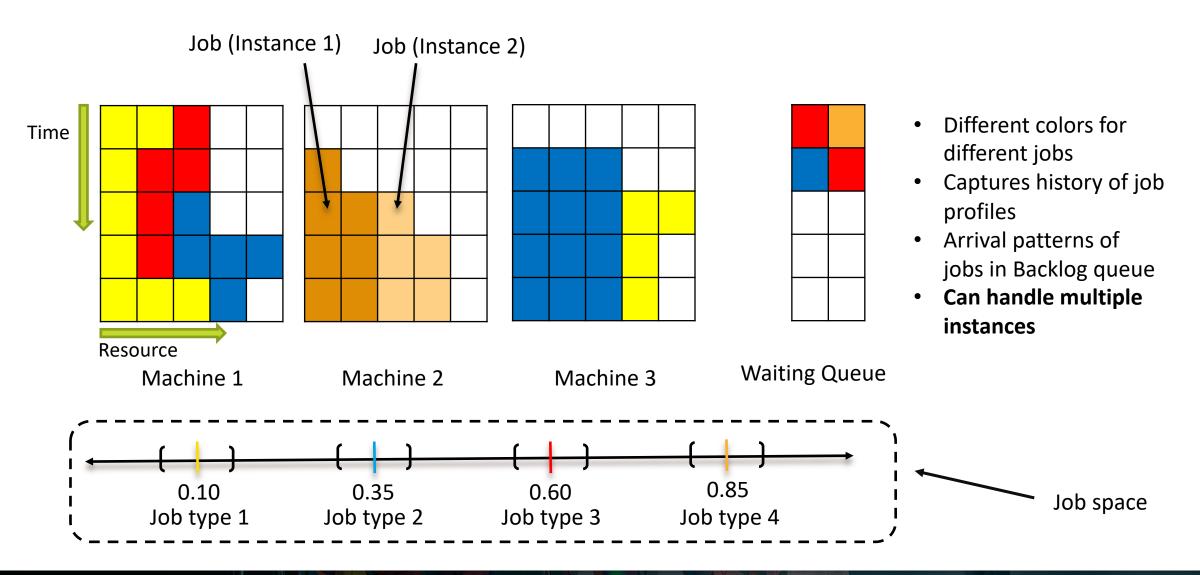


Utilization at current time

### 1. State Representation (4)



# 1. State Representation (5)



### **2. Action Space**

- $A = \{0, 1, 2, ..., M\}$  i.e.  $\{0 \cup \text{Set of machines}\}$
- A<sub>t</sub> = 0 means choosing to not schedule the job.
  - Knowingly delay.
  - Probably better alignment later.
- At a given timestep, multiple actions can be taken.
  - On the set of jobs in the queue.

# 3. Reward Function - Art of Penalizing

- Resource Contention Penalty
  - Prevent resource contention among tasks scheduled in the same machine.
- Resource Over-Utilization Penalty
  - Prevent scheduling of more tasks than can be handled.
- Wait-Time Penalty
  - Prevent the scheduler from holding jobs for a long time.
- Under-Utilization Penalty
  - Improve overall utilization by achieving tighter packing.

$$Cr(i, j, d) = \sum_{t=0}^{\min(Ti,Tj)} res\_usage(i, t, d) \times res\_usage(j, t, d)$$

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 $P_w = -W * |Job Queue|$ 

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$$P_W = -W * |Job Queue|$$

$$P_U = \sum_{m \in \text{used VMs}} \#(unused \ resources_j)$$

# 4. Policy Network

- A Deep Neural Network
- Output Probability distribution over Action Space.
- Learning REINFORCE Algorithm.
- Multiple workers on different examples to accumulate gradients.
  - One worker Combines the gradients.

### **Evaluations – Baselines**

#### DeepRM – RL Agent

- Identifies job to be scheduled next.
- RL agent learns policy to optimize the defined reward.
- Treats cluster as monolithic.
- Doesn't specify where to schedule.
- Fair comparison not possible.
- [DeepRM HotNets'16]

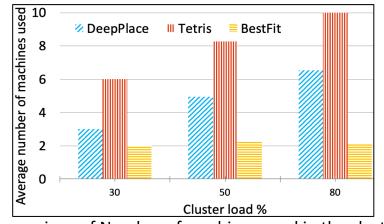
#### Tetris – Heuristic Based

- Schedules jobs on machines.
- How well resource requirement aligns with the machine's available resources.
- Adapts heuristics from multi-dimensional bin packing.
- [Tetris SIGCOMM'14]

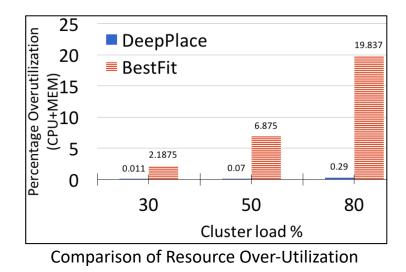
#### BestFit – Heuristic Based

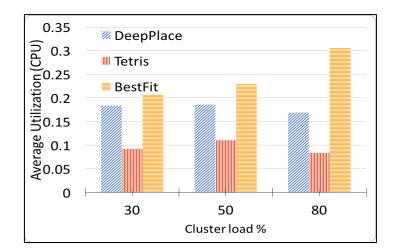
- Schedules jobs on machines.
- Chooses the machine which has the least units of the task's dominant resource available.
- Heuristic closest to packing.

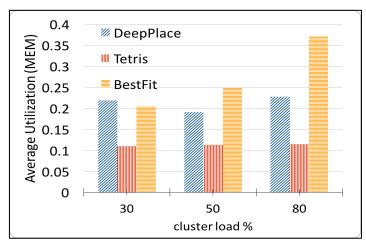
# **Evaluations – Scheduling Efficiency**



Comparison of Number of machines used in the cluster



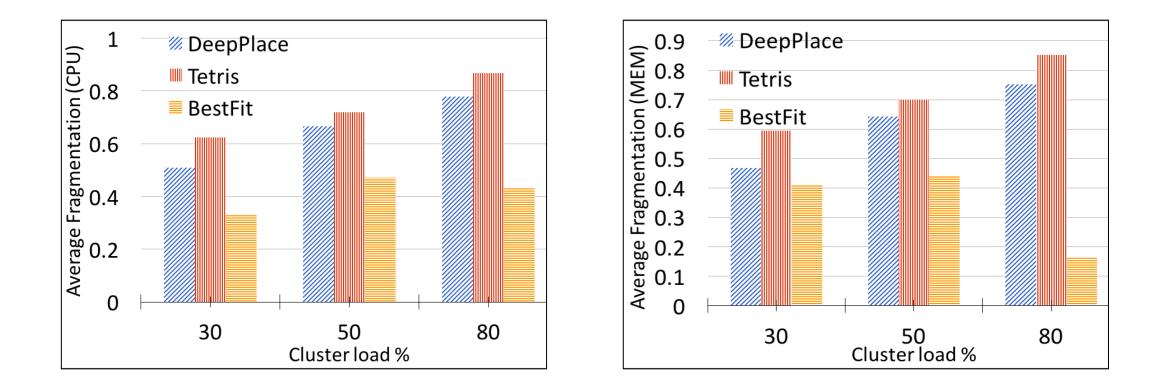




Comparison of Average Resource Utilization in the cluster (CPU and MEM)

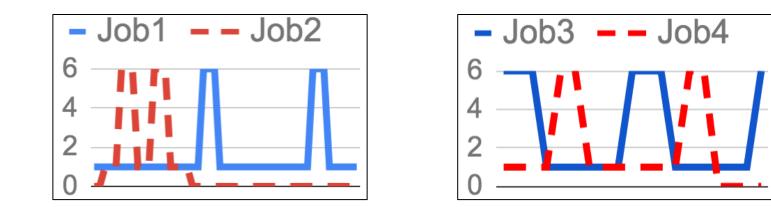
### **Evaluations – Fragmentation**

• We define Average Fragmentation: Avg Frag = 
$$1 - \sum_{t=0}^{T} \frac{\max(\text{available space across all machines at t})}{\text{Sum of available space over all machines at t}}$$



### **Discussions**

- What It Learned?
  - Learned patterns among job's Resource Usages.
  - Ex: Job finishing before peak of other job.
  - Ex: Jobs' with alternating peaks.



## **Discussions - Deployments**

- Scheduling Granularity for effectiveness.
  - Decision Process Frequent or not?
  - Job Length Allows for pattern discovery?
- Boot-strapping Learning.
  - Avoid learning from scratch.
  - Use replays of historical time-series.





### **Future Work**

- Cluster Size Dependency.
  - Input space representation is function of cluster size.
  - Policy learning takes more time to train and converge.
- Evaluation on Real-Life Workloads.
  - Current experimentation on synthetic workloads.
  - Real-life workloads have noisier time-series.

### Conclusion

- Current Multi-Tenant Clusters need to handle variety of services with different type of user expectations and characteristics at production.
- Not possible to design hand-crafted heuristics to orchestrate these services due to numerous latent factors.
- Our self-learning scheduler, DeepPlace, based on Reinforcement Learning shows promise and improvements than heuristics based approaches.



# Thank You! Any Questions?



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